

AGXEED AgBot 5.115T2

Technical Specifications

Drive train

- · 4.1l 4-cylinder Deutz Diesel Engine, stage 5 with 115kW / 156hp, max. torque of 610Nm
- · 350l diesel tank, 30l AdBlue tank
- Optional electric driven PTO (up to 100kW and 700V)

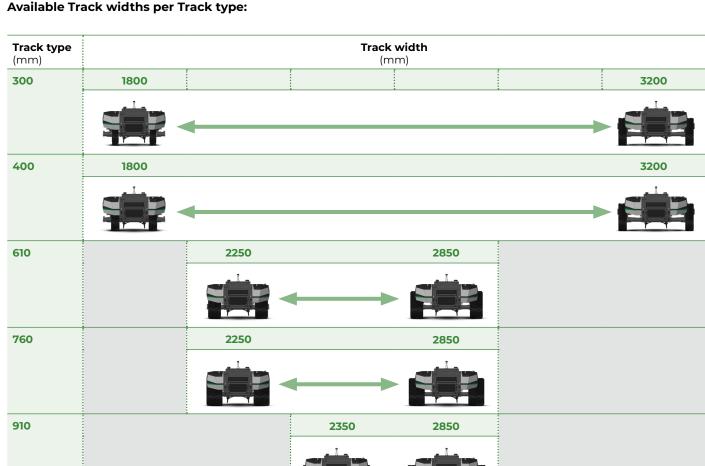
Electric drive train with a speed range from 0-13.5 km/h · Optional HighVoltage connectors (up to 100kW and 700V) based on ISOBUS 11783

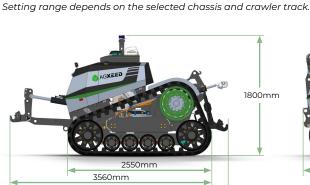
Hydraulics

- · 85I/min at 210bar hydraulic pump
- Up to 4 double-acting proportional spool valves
- · Optional Load Sensing
- · Three-point rear linkage cat 3
- · 8t maximum lift capacity at hooks
- Three-point front linkage cat 2 (hooks cat 3)
- · 3t maximum lift capacity at hooks

Track configuration and Dimensions

- · Variable track width adjustment between 1.800 and 3.000mm or 1.800 3.200mm (range depending on the type of chasse and size of tracks)
- Tracks from 300mm 910mm width
- · Crop clearance 42cm







- · Minimal length: 2550mm
- · Height: 1800mm
- · Total length with hitch at 90 degrees: 2695mm
- · Empty weight: 7,8t

Communication and Positioning RTK GNSS (Real Time Kinematic - Network Global Navigation

3855mm

Satelite System) for precise guidance and safe positioning: ± 2,5cm Communications module for bidirectional data transfer and RTK correction



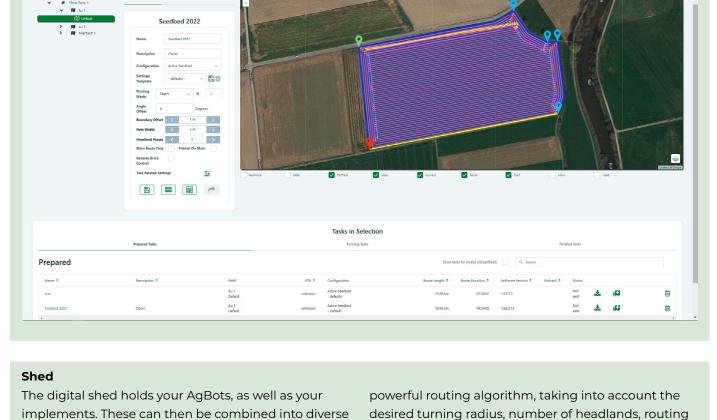
AgXeed Portal

Dashboard The AgXeed portal manages your full business cycle:

fields and tasks and your complete machinery fleet. You will enjoy the well-structured operation screen; find your properties logically arranged by farm, field and part fields. A descend user management lets you decide who will connect to your digital farm. The digital shed hosts your combinations of AgBots with implements including their specific parameters. Once the combinations are created, book them to a alV3 Dashboard **Q** Configs Settings

be stored for later execution, or it can be immediately sent to the combination for execution. Once at the field, you will start the operation with a safe and approved remote control. After the start, everything will work automatically. If you want to check your machine in the meantime, just switch on the camera remotely and check what's going on. That's what we call autonomy. Show Company 1 . Ted Kamps •

specific routing, and the task is created. All tasks can



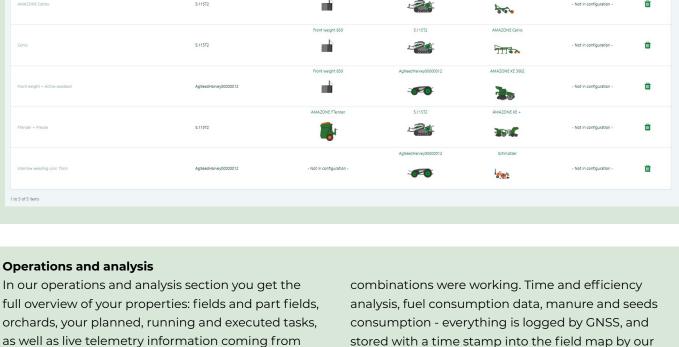
combinations; add a front, rear and top implement like a hopper to configure the machine for your

specific task. All dimensions and available settings are automatically sent to the task management. The whole process is then planned automatically by our **Active Configurations**

boundaries and minimizes the quantity of touching the soil at the same position by the machine. Q Search

mode and overlap. The routing technology takes care,

that the whole field is processed without touching the



your running combinations. Besides all real time

data, this sections also holds the complete history of the information, that was gathered while the

heatmaps. No need for you to think about how it works, it just happens.

